

# PARKA

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# Introduction

What is project PARKA ?

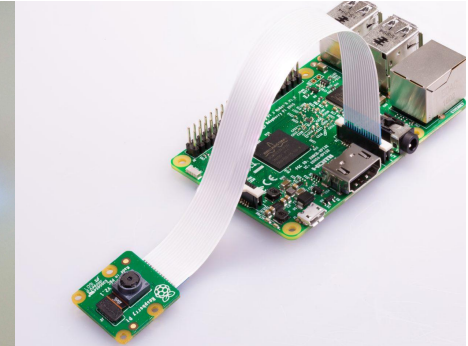
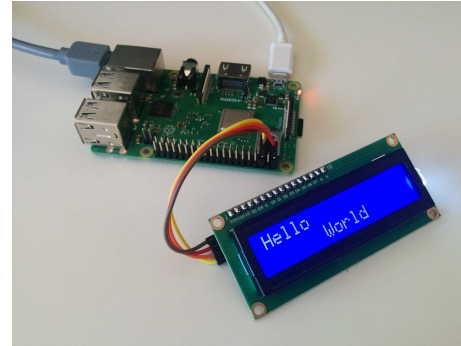
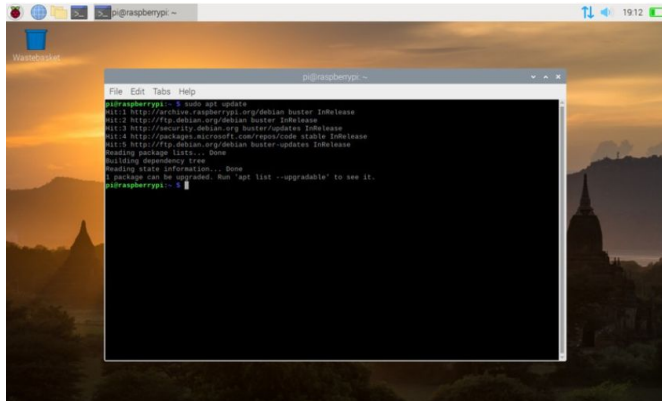
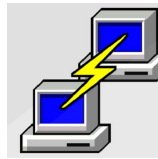
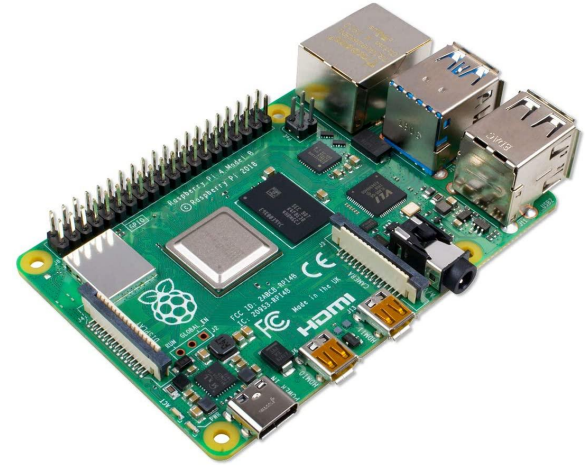
- We are developing a software product that detects the number of empty and occupied spots in a parking lot.
- We're using a Raspberry Pi to run our code which is developed in Python.
- We built a physical model (landscape) to demonstrate how the product works.
- A prototype of a mobile application is being developed; this app will allow users to use the software product.

Why did we chose this Project?

Our team wanted to work on a project that will ultimately help solve an issue students, staff, and faculty face on campus. Developing a product that helps us find parking easily on campus is an idea that we believe is very beneficial.

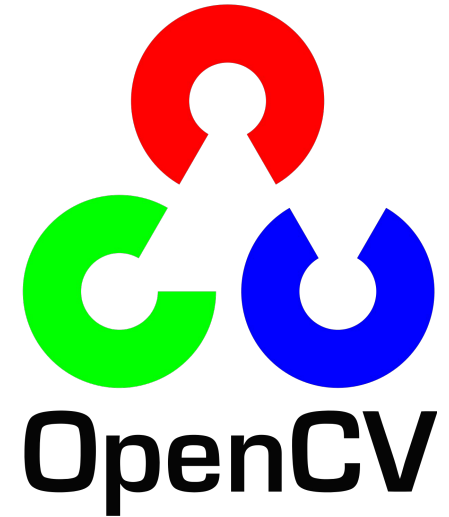
# Raspberry Pi

- Raspbian OS
- Used to Run the program
- VSCode
- WinSCP and Putty was used to gain remote access



# Open CV

- Open Source library
- Real time computer vision
- Virtual environment to manage libraries and Packages used for the project.



# How does the program work?

- Parking spot are defined manually
- All spots are stored in a list
- The list is saved in a file.

```
import cv2
# Package to save parking space positions
import pickle

# capture video from main camera
vid = cv2.VideoCapture(0)
# rectangle measurements
width = 80
height = 130

try:
    with open('CarParking', 'rb') as f:
        poslist = pickle.load(f)
except:
    poslist = []

def click(events,x,y,flags,params):
    if events == cv2.EVENT_LBUTTONDOWN:
        poslist.append((x, y))
    if events == cv2.EVENT_RBUTTONDOWN:
        for i, pos in enumerate(poslist):
            x1, y1 = pos
            if x1 < x < x1 + width and y1 < y < y1 + height:
                poslist.pop(i)

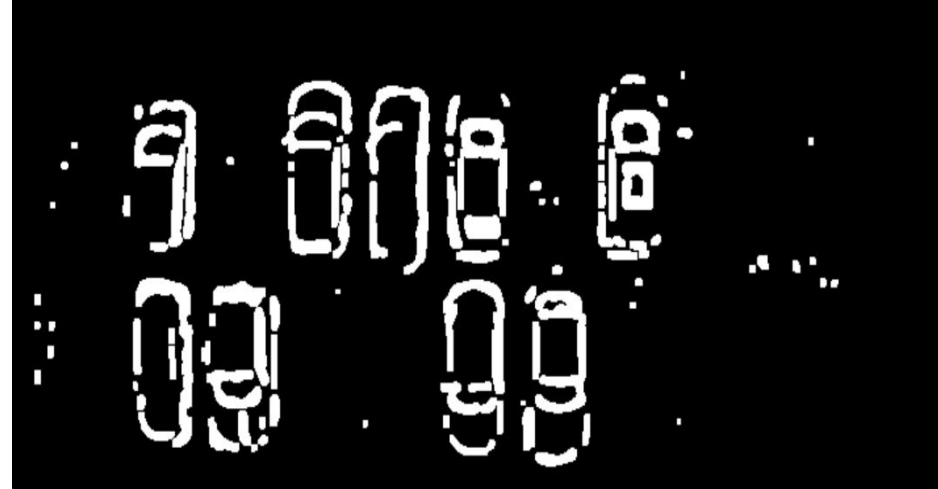
    with open('CarParking', 'wb') as f:
        pickle.dump(poslist, f)

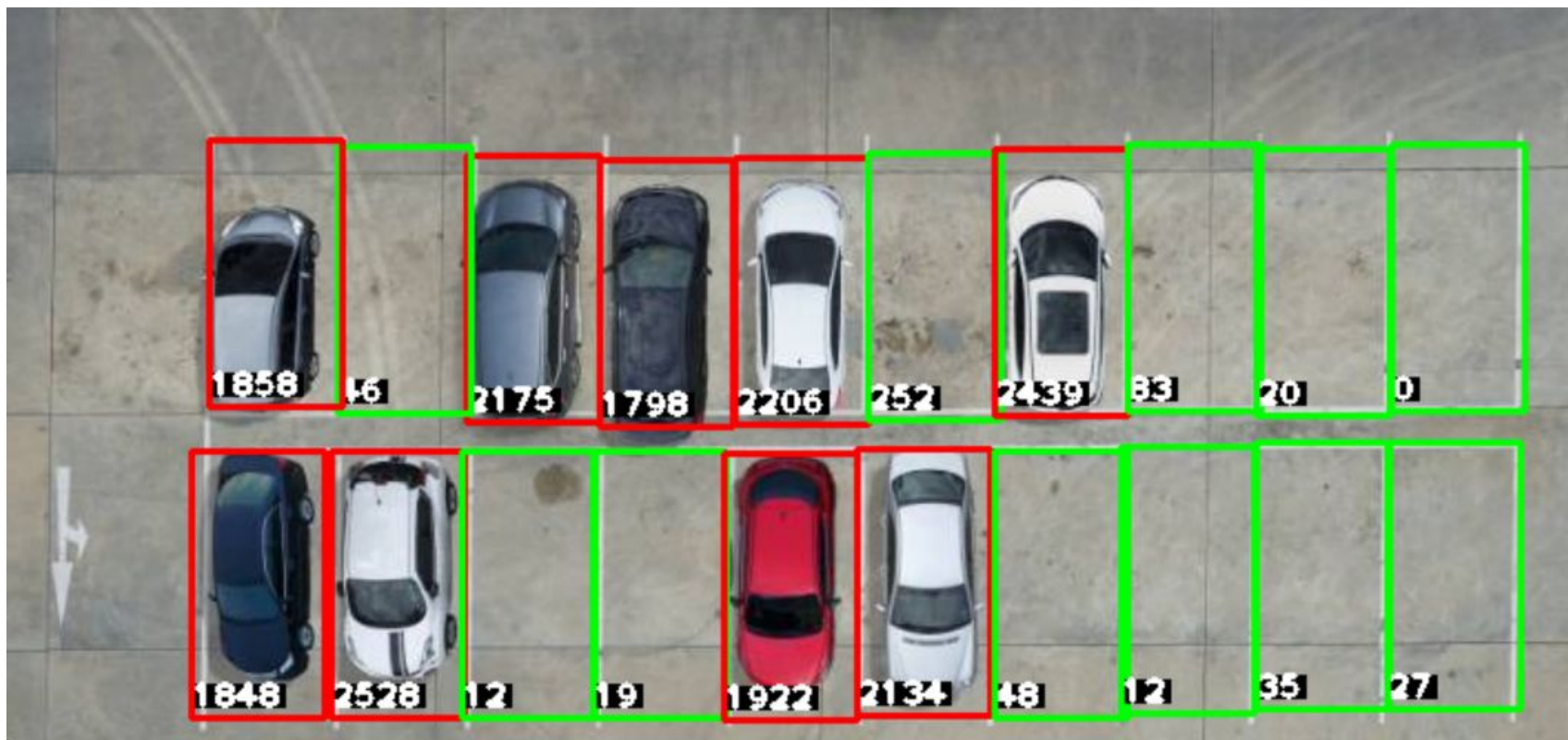
while True:
    # Read image
    ret, image = vid.read()
    #rectangle to represent one parking space
```



# How does the program work ?

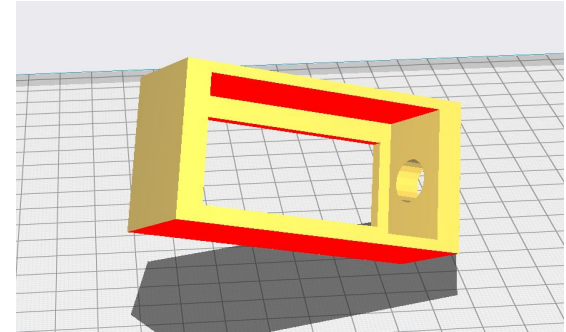
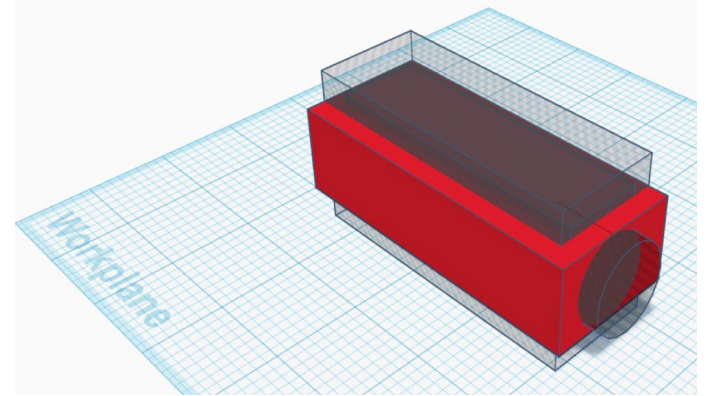
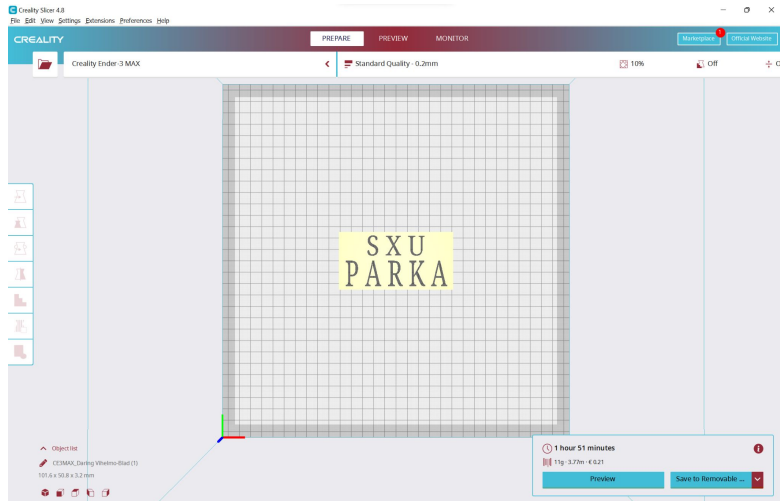
```
7 # create an LCD object and capture video from main camera
8 lcd = LCD()
9 vid = cv2.VideoCapture(0)
10
11
12 # rectangle measurements
13 width = 60
14 height = 120
15
16 #load the parking spots
17 with open('CarParking', 'rb') as f:
18     poslist = pickle.load(f)
19
20 # dunction to check parking spaces
21 def checkspace(imagepro):
22     # declare spaces to zero
23     availableSpace = 0
24
25     # loop through the parking list
26     for pos in poslist:
27         x,y = pos
28         imgcrop = imagepro[y:y+height, x:x+width]
29
30         # count the nonZero pixels
31         count = cv2.countNonZero(imgcrop)
32
33         cvzone.putTextRect(image, str(count), (x,y+height-5), scale = 1, thickness=2, offset=0, colorR=(0,0,0))
34
35         # if pixle is less than 500, then it's empty
36         if count < 500:
37             color = (0,255,0)
38             thickness = 2
39             availableSpace = availableSpace + 1
40
41         # else the spot in not empty
42         else:
43             color = (0,0,255)
44             thickness = 2
45             cv2.rectangle(image,pos,(pos[0] + width, pos[1] + height),color, thickness)
46
47 #print the number of available spaces on the LCD display
48 cvzone.putTextRect(image, f'Available spaces: {availableSpace}/{len(posList)}', (0,30), scale = 2, thickness=2, offset=10, colorR=(0,0,0))
49 lcd.text('Available Spaces',1)
50 lcd.text(" " + str(availableSpace) + " out of " + str(len(poslist)) + " ", 2)
```





# Tinkercad & Ender

- Tinkercad is a 3D modeling program
- Ender is a 3D printer





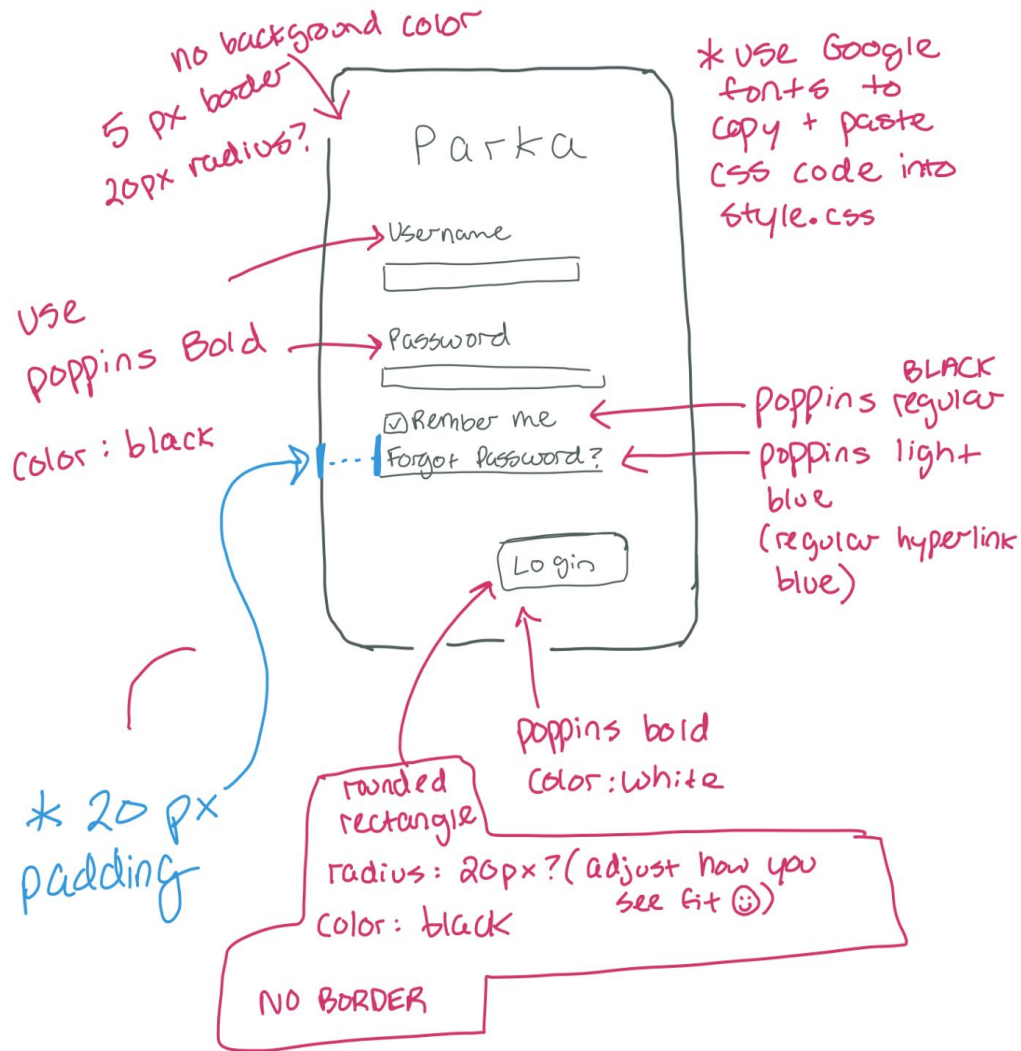
# Revit

Revit is a software used to design and build architectural models



# Webmaster Site Design

- Intended for desktop
- Simple design
- Collaborative effort





**NetID**

**Password**

[Forgot password?](#)

Login

# Webmaster Site

- Secure login
- Access to camera feed
- Ability to run diagnostics tests and reset system
- Warning message before running tests/reset

**P**ARKA

CAMERA 1



CAMERA 2



# PARKA

[View Camera Feed](#) [Run Diagnostics/Reset System](#) [Logout](#)

Select a camera:

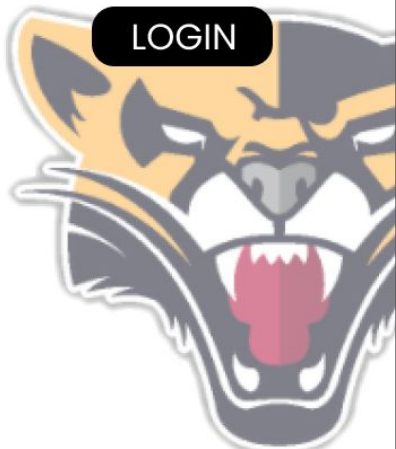
CAMERA 1



# PROTOTYPE

# PARKA

LOGIN



GOOD MORNING,  
COUGS!



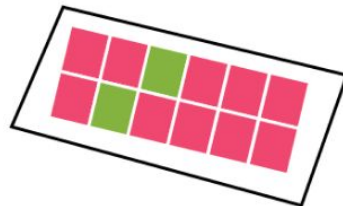
Tap on a **lot** to  
view parking



GOOD MORNING,  
COUGS!



LOT 6



■ - Open

■ - Taken



Spots available

2

★ Add to  
favorites



Settings



Dark Mode



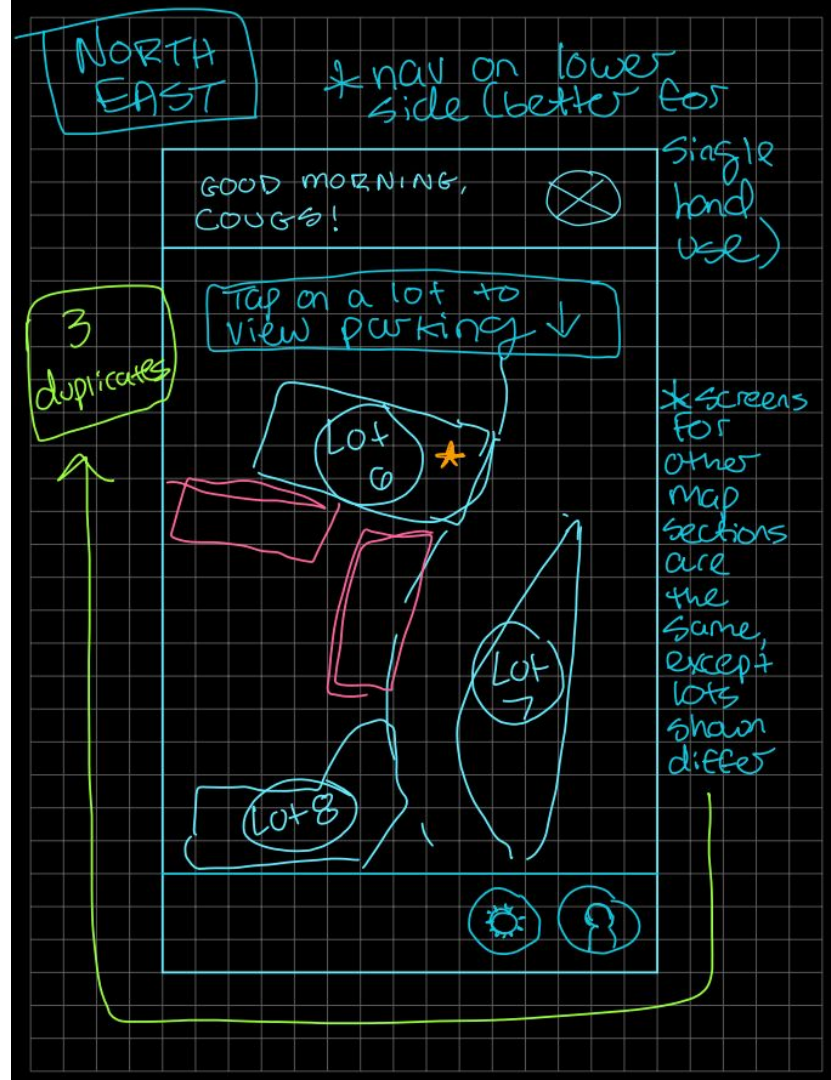
Left Handed

Right Handed

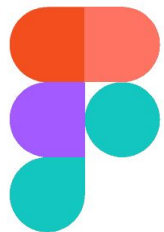
DONE

# Design Goals

- Easy to navigate
- Single-handed use
- Keep it simple
- Fun and clean design







Figma





# Art Assets

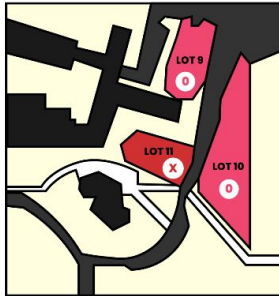
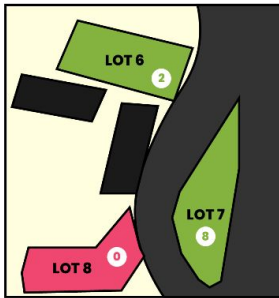
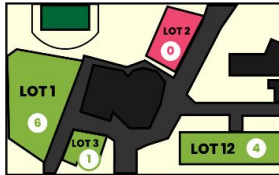
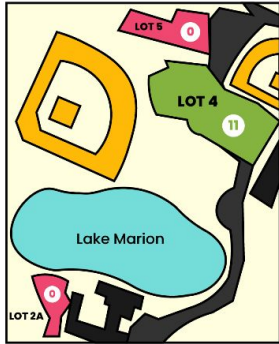
Tap on a **section**  
to view parking ↓



FONT: POPPINS



Tap on a **lot**  
to view parking ↓



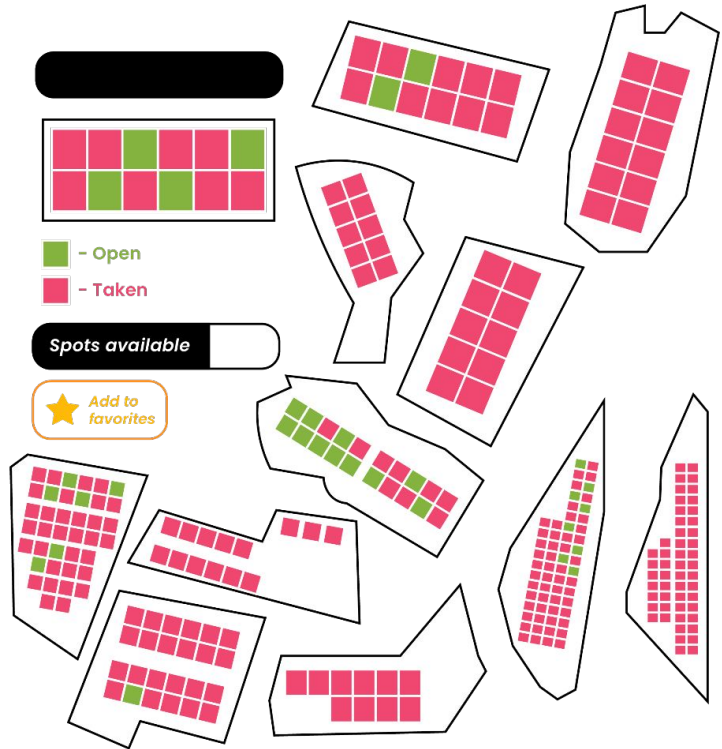
★ Remove from favorites

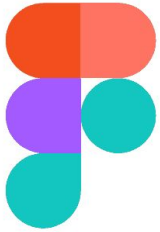


■ - Open  
■ - Taken



★ Add to favorites





# Figma



# Did Tuckman's Ladder apply?

Forming

Storming

Norming

Performing

- What was it like to work in a team?**
- What were your lessons learned?**
- What were your takeaways?**
- What was really difficult?**
- What was easier than you thought it would be?**

# GitHub



## **P**PARKA

# SXU-Software-Engineering

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Dev Team 2

- Amr Alshatnawi
- Alejandra Lopez
- Daniel Carabez
- Karlee Barr

Project PARKA is a project that we are working on for our software engineering class at Saint Xavier University. We are developing a software product that detects the number of empty and occupied spots in a parking lot. We're using a Raspberry Pi to run our code which is developed in Python and we're also building a physical model (landscape) to demonstrate how the product works. A prototype of a mobile application is being developed; this app will allow users to use the software product.

# DEMO

*You ready?*

